

# Pthreads (2)

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# Last Class Review

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- **ANSI/IEEE POSIX1003.1-1995 Standard**
- **Thread management**
  - Work directly on threads – creating, terminating, joining, etc.
  - Include functions to set/query thread attributes.
- **Mutexes**
  - Provide for creating, destroying, locking and unlocking mutexes.
- **Condition variables (Today)**
  - Include functions to create, destroy, wait and signal based upon specified variable values.

# Condition Variables (1)

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- **Another way for thread synchronization**
  - While **mutexes** implement synchronization by controlling thread access to data, **condition variables** allow threads to synchronize based upon the actual value of data.
  - Without condition variables, the programmer would need to have threads **continually polling** to check if the condition is met.
    - This can be *very resource consuming* since the thread would be continuously busy in this activity.
  - A condition variable is *always* used in conjunction with a mutex lock.

# Condition Variables (2)

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- **How condition variables work**

- A thread locks a mutex associated with a condition variable.
- The thread tests the condition to see if it can proceed.
- If it can
  - Your thread does its work
  - Your thread unlocks the mutex
- If it cannot
  - The thread sleeps. **The mutex is automatically released.**
  - Some other threads signals the condition variable.
  - Your thread wakes up from waiting **with the mutex automatically locked**, and it does its work.
  - Your thread releases the mutex when it's done.

# Creating/Destroying CV

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- **Static initialization**

- `pthread_cond_t cond =  
    PTHREAD_COND_INITIALIZER;`

- **Dynamic initialization**

- `pthread_cond_t cond;  
    pthread_cond_init (&cond, (pthread_condattr_t  
    *)NULL);`

- **Destroying a condition variable**

- `pthread_cond_destroy (&cond);`
  - Destroys a condition variable, freeing the resources it might hold.

# Using Condition Variables

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- **int pthread\_cond\_wait** (pthread\_cond\_t \*cond, pthread\_mutex\_t \*mutex)
  - Blocks the calling thread until the specified condition is signalled.
  - This should be called while mutex is locked, and it will automatically release the mutex while it waits.
- **int pthread\_cond\_signal** (pthread\_cond\_t \*cond)
  - Signals another thread which is waiting on the condition variable.
  - Calling thread should have a lock.
- **int pthread\_cond\_broadcast**(pthread\_cond\_t \*cond)
  - Used if more than one thread is in a blocking wait state.

# Producer-Consumer (1)

```
#include <stdio.h>
#include <stdlib.h>
#include <pthread.h>

#define QSIZE          5
#define LOOP          30

typedef struct {
    int data[QSIZE];
    int index;
    int count;
    pthread_mutex_t lock;
    pthread_cond_t notfull;
    pthread_cond_t notempty;
} queue_t;

void *produce (void *args);
void *consume (void *args);
void put_data (queue_t *q, int d);
int get_data (queue_t *q);
```

# Producer-Consumer (2)

```
int main ()
{
    queue_t *q;
    pthread_t producer, consumer;

    q = qinit();

    pthread_create(&producer, NULL, produce, (void *)q);
    pthread_create(&consumer, NULL, consume, (void *)q);

    pthread_join (producer, NULL);
    pthread_join (consumer, NULL);

    qdelete();
}
```



# Producer-Consumer (3)

```
queue_t *qinit()
{
    queue_t *q;

    q = (queue_t *) malloc(sizeof(queue_t));
    q->index = q->count = 0;
    pthread_mutex_init(&q->lock, NULL);
    pthread_cond_init(&q->notfull, NULL);
    pthread_cond_init(&q->notempty, NULL);

    return q;
}

void qdelete(queue_t *q)
{
    pthread_mutex_destroy(&q->lock);
    pthread_cond_destroy(&q->notfull);
    pthread_cond_destroy(&q->notempty);
    free(q);
}
```

# Producer-Consumer (4)

```
void *produce(void *args)
{
    int i, d;
    queue_t *q = (queue_t *)args;
    for (i = 0; i < LOOP; i++) {
        d = random() % 10;
        put_data(q, d);
        printf("put data %d to queue\n", d);
    }
    pthread_exit(NULL);
}

void *consume(void *args)
{
    int i, d;
    queue_t *q = (queue_t *)args;
    for (i = 0; i < LOOP; i++) {
        d = get_data(q);
        printf("got data %d from queue\n", d);
    }
    pthread_exit(NULL);
}
```

# Producer-Consumer (5)

```
void put_data(queue_t *q, int d)
{
    pthread_mutex_lock(&q->lock);
    while (q->count == QSIZE) pthread_cond_wait(&q->notfull, &q->lock);
    q->data[(q->index + q->count) % QSIZE] = d;
    q->count++;
    pthread_cond_signal(&q->notempty);
    pthread_mutex_unlock(&q->lock);
}

int get_data(queue_t *q)
{
    int d;
    pthread_mutex_lock(&q->lock);
    while (q->count == 0) pthread_cond_wait(&q->notempty, &q->lock);
    d = q->data[q->index];
    q->index = (q->index + 1) % QSIZE;
    q->count--;
    pthread_cond_signal(&q->notfull);
    pthread_mutex_unlock(&q->lock);
    return d;
}
```

# Thread Safety (1)

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- **Thread-safe**
  - Functions called from a thread must be **thread-safe**.
  - We identify four (non-disjoint) classes of thread-unsafe functions:
    - Class 1: Failing to protect shared variables
    - Class 2: Relying on persistent state across invocations
    - Class 3: Returning a pointer to a static variable
    - Class 4: Calling thread-unsafe functions

# Thread Safety (2)

- **Class 1: Failing to protect shared variables.**
  - Fix: Use mutex operations.
  - Issue: Synchronization operations will slow down code.

```
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
int cnt = 0;

/* Thread routine */
void *count(void *arg) {
    int i;

    for (i=0; i<NITERS; i++) {
        pthread_mutex_lock (&lock);
        cnt++;
        pthread_mutex_unlock (&lock);
    }
    return NULL;
}
```

# Thread Safety (3)

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- **Class 2: Relying on persistent state across multiple function invocations.**
  - Random number generator relies on static state
  - Fix: Rewrite function so that caller passes in all necessary state.

```
/* rand - return pseudo-random integer on 0..32767 */
int rand(void) {
    static unsigned int next = 1;
    next = next*1103515245 + 12345;
    return (unsigned int)(next/65536) % 32768;
}
/* srand - set seed for rand() */
void srand(unsigned int seed) {
    next = seed;
}
```

# Thread Safety (4)

- **Class 3: Returning a ptr to a static variable.**

- **Fixes:**

1. Rewrite code so caller passes pointer to **struct**.

- Issue: Requires changes in caller and callee.

```
struct hostent
*gethostbyname(char *name){
    static struct hostent h;
    <contact DNS and fill in h>
    return &h;
}
```

```
hostp = malloc(...));
gethostbyname_r(name, hostp);
```

2. *Lock-and-copy*

- Issue: Requires only simple changes in caller (and none in callee)
  - However, caller must free memory.

```
struct hostent
*gethostbyname_ts(char *name)
{
    struct hostent *unshared
        = malloc(...);
    pthread_mutex_lock(&lock); /* lock */
    shared = gethostbyname(name);
    *unshared = *shared; /* copy */
    pthread_mutex_unlock(&lock);
    return q;
}
```

# Thread Safety (5)

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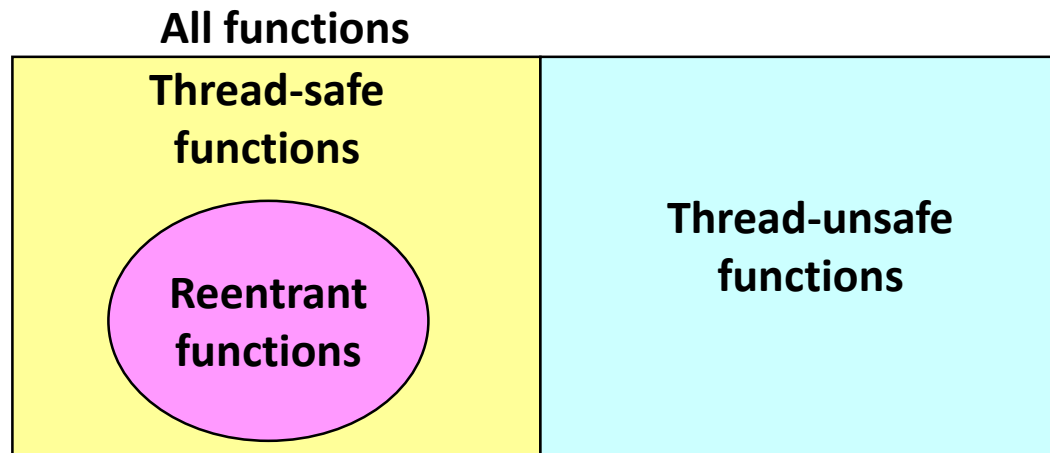
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- **Class 4: Calling thread-unsafe functions.**
  - Calling one thread-unsafe function makes an entire function thread-unsafe.
  - Fix: Modify the function so it calls only thread-safe functions



# Reentrant Functions

- A function is ***reentrant*** iff it accesses **NO** shared variables when called from multiple threads.
  - Reentrant functions are a proper subset of the set of thread-safe functions.



- NOTE: The fixes to Class 2 and 3 thread-unsafe functions require modifying the function to make it reentrant.

# Thread-Safe Library

- All functions in the Standard C Library (at the back of your K&R text) are thread-safe.
  - Examples: **malloc**, **free**, **printf**, **scanf**
- Most Unix system calls are thread-safe, with a few exceptions:

Thread-unsafe function	Class	Reentrant version
asctime	3	asctime_r
ctime	3	ctime_r
gethostbyaddr	3	gethostbyaddr_r
gethostbyname	3	gethostbyname_r
inet_ntoa	3	(none)
localtime	3	localtime_r
rand	2	rand_r

- 아래의 내용을 **conditional variable**을 사용하여 구현 후, 자신의 프로그램이 잘 작동함을 증명
  - 가정
    - deposit(): 수당을 받음
    - withdraw(): 카드 값이 빠져나감
  - 조건
    - 하나의 카드 값은 나눠서 빠져나가지 않는다.
    - 카드 값이 빠져나간 후의 잔고는 0원보다 작을 수 없다.
    - 카드 값은 잔고가 충분해 지면 즉시 출금된다.